



- Calibration Assumptions:**
- Weights Are Present
 - Mass of Weights Are Known
 - Calibration Arm Length is Known
 - Operator Has Access to the Front of the Dyn-Loc IV Dynamometer Controller

- Defined Variables:**
- d = Distance From the Center of Shaft to the Weight Hanger Pin
 - T = Computed Simulated Torque
 - W = Calibration Weight